www.ijlemr.com || Volume 05 - Issue 07 || July 2020 || PP. 20-25

Ricci Solitons on (ε) -Para Sasakian Manifolds Admitting **Concircular Curvature Tensor**

R. L. Patel¹, S.K. Pandey² and R. N. Singh³

Department of Mathematical Sciences, A. P. S. University, Rewa-486003 (M.P.) India

Abstract: The object of the present paper is to study Ricci solitons in (ε) -para Sasakian manifolds satisfying $S(\xi, X).\overline{C}=0$, $R(\xi, X).\overline{C}=0$, $\overline{C}(\xi, X).S=0$, $\overline{C}(\xi, X).R=0$, $R(\xi, X).\overline{C}=0$, where \overline{C} is concircular curvature tensor.

2010 Mathematics Subject Classification: 53C25,53C15. **Keywords:** (ε)-para Sasakian manifolds, Ricci solitons, concircular curvature tensor, space-like vector field, light-like vector field.

1. Introduction:

In the differential geometry, the Ricci flow is an intrinsic geometric flow, which was introduced by R. Hamilton ([11], [12]). The Ricci flow is a process that deforms the metric of a Riemannian manifold in a way formally analogous to the diffusion of heat, smoothing our irregularities in the metric. The Ricci flow equation is the evolution equation

$$\frac{\mathrm{d}}{\mathrm{d}t}g_{ij}(t) = -2 \mathrm{R}_{ij}$$

 $\frac{\mathrm{d}}{\mathrm{dt}}g_{ij}(t) = -2\ \mathrm{R}_{ij}$ for a Riemannian metric g_{ij} , where R_{ij} is the Ricci curvature tensor. Hamilton showed that there is a unique solution to this equation for an arbitrary smooth metric g_{ii} . Hamilton on a closed manifold over a sufficient short time. He also showed that Ricci flow preserves positivity of Ricci curvature tensor in three dimensions and the curvature operator in all dimensions. Ricci solitons are Ricci flows that may change their size but not their shape up to diffeomorphisms.

A significant 2-dimensional example of Ricci soliton is the cigar solution which is given by the metric $(dx^2 + dy^2)/(e^{4t} + x^2 + y^2)$ on the Euclidean plane. Although this metric shrinks under the Ricci flow, its geometry remains the same. Such a solutions are called steady Ricci solitons.

A Ricci soliton is a triple (g, v, λ) with g a Riemannian metric, v a vector field and λ a real scalar such that

$$(\mathcal{L}_{V}g)(X, Y) + 2S(X, Y) + 2\lambda g(X, Y) = 0,$$
 (1.1)

where S is a Ricci tensor of M^n and \mathcal{L}_V denote the Lie –derivative along the vector field V. The Ricci soliton is said to be shrinking, steady and expanding accordingly as real scalar λ is negative, zero and positive respectively. Ricci solitons were studied by several authors in contact and Lorentzian manifold, Para Sasakian manifold such as Sharma [20], Bagewadi and Ingalahalli [1], Nagaraja and Premalatha [15], Bagewadi [1], Pandey, Patel and Singh [17] et all and others.

On the other hand, the study of manifolds with indefinite metrics is of interest from the stand point of physics and relativity. Manifolds with indefinite metrics have been studied by several authors. In 1993, Bejancu and Duggal [3] introduced the concept of (ε) -Sasakian manifolds and Xufeng and Xiaoli [22] established that these manifolds are real hyper-surfaces of indefinite Kahlerian manifolds. De and Sarkar [7] introduced (ε)-para Sasakian manifolds and studied some curvature conditions on it. Singh, Pandey, Pandey and Tiwari [16], Patel, Pandey and Singh {[18],[19]}, established the relation between semi-symmetric metric connection and Riemannian connection on (ε) -para Sasakian manifolds and have studied several curvature conditions.

Motivated by these studies, we study Ricci solitons in (ε) -para Sasakian manifolds. In this paper, we have studied Ricci solitons in (ε) -para Sasakian manifolds satisfying $S(\xi, X).\overline{C} = 0$, $R(\xi, X).\overline{C} = 0$, $\overline{C}(\xi, X).\overline{C} = 0$ X).S=0, $\bar{C}(\xi, X)$.R =0, R(ξ, X). \bar{C} =0, where \bar{C} is concircular curvature tensor of the manifold.

2. (ε) -Para Sasakian manifolds:

Let M^n be an almost paracontact manifold equipped with an almost paracontact structure (ϕ, ξ, η) consisting of a tensor field ϕ of type (1,1), a vector field ξ and a one η satisfying

$$\phi^2 X = X - \eta(X)\xi, \tag{2.1}$$

$$\eta(\xi) = 1, \tag{2.2}$$

$$\phi(\xi) = 0, \tag{2.3}$$

and

$$\eta o \phi = 0. \tag{2.4}$$

www.ijlemr.com || Volume 05 - Issue 07 || July 2020 || PP. 20-25

Let Mⁿ be an n-dimensional almost paracontact manifold and g be semi-Riemannian metric with index (g)=v such that

$$g(\phi X, \phi Y) = g(X, Y) - \varepsilon \eta(X) \eta(Y), \tag{2.5}$$

where $\varepsilon = \pm 1$. In this case, Mⁿ is called an (ε) -almost paracontact metric manifold equipped with an (ε)-almost paracontact structure (ϕ, ε, n, q),[18]. In particular, if index (q)=1, then an (ε)-almost paracontact metric manifold will be called a Lorentzian almost paracontact manifold. If in case, the metric is positive definite, then an (ε) -almost paracontact metric manifold is the almost paracontact metric manifold. In view of equations (4), (5) and (7), we have

$$g(\phi X, Y) = g(X, \phi Y) \tag{2.6}$$

and

$$\varepsilon g(X, \xi) = \eta(X),$$
 (2.7)

 $\epsilon g(X,\xi) = \eta(X),$ for every $X,Y \epsilon$ $TM^n.$ From equation (9), it follows that

$$\varepsilon = g(\xi, \, \xi),\tag{2.8}$$

i.e. the structure of vector field ξ is never light-like. An (ε) -almost paracontact metric manifold (resp., a Lorentzian almost paracontact manifold $(M^n, \phi, \xi, g, \varepsilon)$ [18], is said to space-like (ε) -almost paracontact metric manifold (respectively a space-like Lorentzian almost paracontact manifold), if $\varepsilon = 1$ and Mⁿ is said to be a time-like (ε)-almost paracontact manifold (respectively a Lorentzain almost paracontact manifold) if $\varepsilon = -1$. An (ε) -almost paracontact metric structure is called an (ε) -Para Sasakian structure if

$$(\nabla_{\mathbf{X}} \mathbf{\Phi})(\mathbf{Y}) = -g(\mathbf{X}, \mathbf{\Phi}\mathbf{Y})\xi - \epsilon \mathbf{\eta}(\mathbf{Y})\mathbf{\Phi}^{2}\mathbf{X}, \qquad \mathbf{X}, \mathbf{Y} \boldsymbol{\epsilon} \mathbf{T} \mathbf{M}^{n}, \tag{2.9}$$

where ∇ is the Levi-Civita connection. A manifold Mⁿ endowed with an (ε) -para Sasakian structure is called an (ε)-para Sasakian manifold. For $\varepsilon = 1$ and g Riemannian metric, M^n is the usual para Sasakian manifold [18]. For ε =-1, g Larentzian metric and ξ replaced by $-\xi$, Mⁿ becomes a Lorentzian para Sasakian manifold. In an (ε) -para Sasakian manifold, we have

$$\nabla_{X} \xi = \varepsilon \varphi X,$$
 (2.10)

$$\Omega(X, Y) = \varepsilon g(\phi X, Y) = (\nabla_X \eta)(Y), \tag{2.11}$$

for every X, Y \in TMⁿ, where Ω is the fundamental 2-form. In an (ε) -almost para Sasakian manifold Mⁿ, the following relations holds.

$$R(\xi, X)Y = -\varepsilon g(X, Y)\xi + \varepsilon \eta(Y)X, \tag{2.12}$$

$$R(X, Y)\xi = -\varepsilon \eta(Y)X + \varepsilon \eta(X)Y. \tag{2.13}$$

In an n-dimensional (ε)-para Sasakian manifold M^n , the Ricci tensor S satisfies

$$\eta(R(X, Y)Z) = \varepsilon[g(Y, Z)\eta(X) - g(X, Z)\eta(Y)]. \tag{2.14}$$

Let (g, V, λ) be a Ricci solitons in an (ε) -Kenmotsu manifold. From equation (2.9), we have

$$(L_{\varepsilon}g)(X, Y) = -2[\varepsilon g(X, Y) - \eta(X)\eta(Y)]. \tag{2.15}$$

In view of equations (1.1) and (2.15), we have

$$S(X, Y) = [\varepsilon q(\phi X, Y) - \lambda q(X, Y)], \tag{2.16}$$

yields that

$$S(X, \xi) = -\varepsilon \lambda \eta(X)$$
,

(2.17)

$$QX = \varepsilon \varphi X - \lambda X, \qquad (2.18)$$

$$r = n \left[\varphi X - \lambda X \right]. \qquad (2.19)$$

The concircular curvature tensor
$$\overline{C}$$
 is defined as [14]
$$\overline{C}(X, Y)Z = R(X, Y)Z - \frac{r}{n(n-1)}[g(Y, Z)X - g(X, Z)Y]. \tag{2.20}$$

By virtue of equations (2.7) and (2.12), and using equation (2.20) as $X=\xi$, the concircular curvature tensor on

(
$$\epsilon$$
)-Para Sasakian manifold takes the form
$$\bar{\mathbb{C}}(\xi, \mathbf{Y})\mathbf{Z} = -[\varepsilon + \frac{r}{n(n-1)}]g(\mathbf{Y}, \mathbf{Z})\xi + [\varepsilon + \frac{r\varepsilon}{n(n-1)}]\eta(\mathbf{Z})\mathbf{Y}],$$
 (2.21)

Again on putting Z= ξ , in equation (2.20) and by the use of equation (2.2), (2.3), (2.7) and (2.13), we obtain $\overline{C}(X,Y)\xi = -[1+\frac{r}{n(n-1)}][\epsilon\eta(Y)X - \epsilon\eta(X)Y]. \tag{2.23}$

$$\overline{C}(X, Y)\xi = -[1 + \frac{r}{n(n-1)}][\varepsilon \eta(Y)X - \varepsilon \eta(X)Y]. \tag{2.23}$$

which gives

$$\eta(\bar{C}(X, Y)Z) = \left[\varepsilon - \frac{r}{n(n-1)}\right] [g(Y, Z)\eta(X) - g(X, Z)\eta(Y)]. \tag{2.24}$$

Example: Let R³ be the 3-dimensional real number space with a co-ordinate system (X,Y,Z) we define
$$\eta$$
=dz-Ydx, $\xi = \frac{\partial}{\partial Z}$, $\phi\left(\frac{d}{dx}\right) = -\frac{d}{dx} - y\frac{d}{dz}$, $\phi\left(\frac{d}{dy}\right) = -\frac{d}{dy}$, $\phi\left(\frac{d}{dz}\right) = 0$, www.ijlemr.com

International Journal of Latest Engineering and Management Research (IJLEMR)

ISSN: 2455-4847

www.ijlemr.com || Volume 05 - Issue 07 || July 2020 || PP. 20-25

$$g_1 = (dx)^2 + dy^2 - \eta \otimes \eta,$$

$$g_2 = (dx)^2 + (dy)^2 + (dz)^2 - y(dx \otimes dz + dz \otimes dx),$$

$$g_3 = -(dx)^2 + (dy)^2 + (dz)^2 - y(dx \otimes dz + dz \otimes dx).$$

Then the (ϕ, ξ, η) is an almost paracontact structure in \mathbb{R}^3 . The set the (ϕ, ξ, η, g_1) is a time –like Lorentzain paracontact structure. Moreover, trajectories of the time-like structure vector ξ are geodesics. The set (ϕ, ξ, η, q_2) is space-like Lorentzian almost paracontact structure. The set the (ϕ, ξ, η, q_3) is a space-like (ε) almost paracontact structure the $(\phi, \xi, \eta, g_3, \varepsilon)$ with index $(g_3)=2$.

3. Ricci Solitons in (ε) -Para Sasakian Manifolds Satisfying $S(\xi,X).\bar{C}=0$

Using the following equations

$$S(X,\xi).\overline{C})(Y,Z)U = ((X\Lambda_S\xi).\overline{C})(Y, Z)U$$

$$= (X\Lambda_S\xi)\overline{C}(Y, Z)U + \overline{C}((X\Lambda_S\xi)(Y, Z)U)$$

$$+\overline{C}(X,(X\Lambda_S\xi)Y)U) + \overline{C}(Y, Z)(X\Lambda_S\xi)U,$$
(3.1)

where the endomorphism $(X \Lambda_S Y)$ is defined by

$$(X \wedge_{S} Y)Z = S(Y, Z)X - S(X, Z)Y. \tag{3.2}$$

Now, from equations (3.1) and (3.2), we have

$$(S(X, \xi).\overline{C})(Y, Z)U = S(\xi, \overline{C}(Y, Z)U)X - S(X, \overline{C}(Y, Z)U)\xi + S(\xi, Y)\overline{C}(X, Z)U) -S(X, Y)\overline{C}(\xi, Z)U + S(\xi, Z)\overline{C}(Y, X)U - S(X, Z)\overline{C}(Y, \xi)U +S(\xi, U)\overline{C}(Y, Z)X - S(X, U)\overline{C}(Y, Z)\xi.$$
(3.3)

Assuming $(S(X, \xi), \overline{C})(Y, Z)U = 0$, then above equation reduces to

$$S(\xi, \overline{C}(Y, Z)U)X - S(X, \overline{C}(Y,Z)U)\xi + S(\xi, Y)\overline{C}(X, Z)U - S(X, Y)\overline{C}(\xi, Z)U + S(\xi, Z)\overline{C}(Y, X)U - S(X, Z)\overline{C}(Y, \xi)U + S(\xi, U)\overline{C}(Y, Z)X - S(X, U)\overline{C}(Y, Z)\xi = 0.$$
(3.4)

Taking the inner product of above equation with ξ and using equation (2.3), (2.7), we get

 $\varepsilon \eta(X) S(\xi, \overline{C}(Y, Z)U) - S(X, \overline{C}(Y, Z)U) + \varepsilon S(\xi, Y) \eta(\overline{C}(X, Z)U) - \varepsilon S(X, Y) \eta(\overline{C}(\xi, Z)U)$

$$+\varepsilon S(\xi, Z)\eta(\bar{C}(Y, X)U) - \varepsilon S(X, Z)\eta(\bar{C}(Y, \xi)U) +\varepsilon S(\xi, U)\eta(\bar{C}(Y, Z)X) - \varepsilon S(X, U)\eta(\bar{C}(Y, Z)\xi) = 0.$$
 (3.5)

In virtue of above equations (2.17) and (2.23), we get

$$S(X, \overline{C}(Y, Z)U) = \left[\varepsilon - \frac{r}{n(n-1)}\right] \left[-\varepsilon S(X, Y)g(Z, U) + S(X, Y)\eta(U)\eta(Z) - S(X, Z)\eta(U)\eta(Y) + \varepsilon S(X, Z)g(Y, U) - \lambda g(Z, X)\eta(U)\eta(Y) + \lambda g(Y, X)\eta(U)\eta(Z)\right],$$
(3.6)

which by virtue of equation (2.5) and (2.17) in Putting $Y=\xi$, gives

$$\left[\varepsilon - \frac{r}{n(n-1)}\right] \lambda \left[(1-\varepsilon) \left\{ g(Z, U)\eta(Y) - g(Y, U)\eta(Z) \right\} - 2\varepsilon \eta(Y)\eta(U)\eta(Z) \right] = 0. \tag{3.7}$$

Putting Z=U= e_i and taking summation over i, $1 \le i \le n$, we get

$$\left[\varepsilon - \frac{r}{r(r-1)}\right] 2\lambda(1+\varepsilon)\eta(Y) = 0. \tag{3.8}$$

Putting Z=U=e_i and taking summation over i,
$$1 \le i \le n$$
, we get
$$\left[\varepsilon - \frac{r}{n(n-1)} \right] 2\lambda(1+\varepsilon)\eta(Y) = 0.$$
 In virtue of equations (2.5), (2.2) and (2.3) Putting $Y = \xi$, we get
$$\left[\varepsilon - \frac{r}{n(n-1)} \right] 2\lambda(1+\varepsilon) = 0.$$
 (3.9)
$$\lambda = 0 \text{ or } \left[\varepsilon - \frac{r}{n(n-1)} \right] = 0,$$
 which shows that λ is steady. Thus we can state as follows -

which shows that λ is steady. Thus we can state as follows -

Theorem (3.1): Ricci Soliton in (ε) -para Sasakian manifolds with ξ as space-like vector field satisfying $S(\xi, X).\overline{C} = 0$, λ is steady.

Now, suppose ξ is space –like vector field in (ε) -para Sasakian manifolds, then from equation (3.8), we obtain $\lambda = 0$ or $\lambda > 0$,

which shows that λ is either steady or shrinking. Thus we can state as follows -

Theorem (3.2): Ricci Soliton in (ε) -para Sasakian manifolds with ξ as space-like vector field satisfying $S(\xi, X).\overline{C} = 0$, is either steady or shrinking.

4. Ricci Soliton in (ε) -Para Sasakian Satisfying $R(\xi, X).\overline{C} = 0$.

Let us suppose $R(\xi, X).\overline{C} = 0$, that is

$$(R(\xi, X).\overline{C})(Y,Z)U=0,$$

which gives

$$R(\xi, X)\overline{C}(Y, Z)U - \overline{C}(R(\xi, X)Y, Z)U - \overline{C}(Y, R(\xi, X)Z)U - \overline{C}(Y, Z)R(\xi, X)U = 0. \tag{4.1}$$

www.ijlemr.com || Volume 05 - Issue 07 || July 2020 || PP. 20-25

In view of equation (2.14), above equation reduces to

$$\varepsilon\eta(\bar{C}(Y, Z)U)X - \varepsilon g(X, \bar{C}(Y, Z)U)\xi + \varepsilon g(X, Y)\bar{C}(\xi, Z)U + \varepsilon\eta(Y)\bar{C}(X, Z)U
+ \varepsilon g(X, Z)\bar{C}(Y, \xi)U - \varepsilon\eta(Z)\bar{C}(Y, X)U
+ \varepsilon g(X, U)\bar{C}(Y, Z)\xi - \varepsilon\eta(U)\bar{C}(Y, Z)X = 0.$$
(4.2)

Now, taking the inner product of above equation with ξ , and using equation (2.2) and (2.3), we get

$$\eta(X)\eta(\overline{C}(Y, Z)U) - \varepsilon g(X, \overline{C}(Y,Z)U) + g(X, Y)\eta(\overline{C}(\xi, Z)U) + \eta(Y)\eta(\overline{C}(X, Z)U)
+ g(X, Z)\eta(\overline{C}(Y, \xi)U) - \eta(Z)\eta(\overline{C}(Y, X)U)
+ g(X, U)\eta(\overline{C}(Y, Z)\xi) - \eta(U)\eta(\overline{C}(Y, Z)X) = 0.$$
(4.3)

By virtue of equation (2.24), above equation takes the form

$$\epsilon g(X, \overline{C}(Y, Z)U) = K_2[-(\epsilon - 1)\{-g(X, Y)\eta(Z) + g(X, Z)\eta(Y)\}\eta(U)
+2g(Z, U)\eta(X)\eta(Y) - g(Y, U)\eta(X)\eta(Z) - g(X, U)\eta(Y)\eta(Z)
-g(X, Z)g(Y, U) - g(X, Y)g(Z, U)].$$
(4.4)

which on putting $X=\xi$, we get

$$K_2[g(Z, U)\eta(Y) - \varepsilon\eta(U)\eta(Y)\eta(Z) + (\varepsilon - 1)g(Z, U)\eta(Y) - \varepsilon g(Y, U)\eta(Z)] = 0, \tag{4.5}$$

Putting $Y=Z=\xi$ using equation, we get

$$K_2[3\varepsilon\eta(U)] = 0$$
, where $K_2 = [\varepsilon - \frac{r}{n(n-1)}]$ (4.6)

In view of equation $U=\xi$, we get

$$K_{2}[3\varepsilon\eta(U)] = 0, \text{ where } K_{2} = [\varepsilon - \frac{r}{n(n-1)}]$$
we get
$$\varepsilon[\varepsilon - \frac{r}{n(n-1)}] = 0, \text{ where } r = n(\phi X - \lambda X)$$

$$\varepsilon[\varepsilon - \frac{(\phi \xi - \lambda \xi)}{(n-1)}] = 0,$$

$$\lambda < 0,$$
where $\kappa_{2} = [\varepsilon - \frac{r}{n(n-1)}]$

$$\kappa_{3} = [\varepsilon - \frac{(\phi \xi - \lambda \xi)}{(n-1)}] = 0,$$
where $\kappa_{2} = [\varepsilon - \frac{r}{n(n-1)}]$

$$\kappa_{3} = [\varepsilon - \frac{(\phi \xi - \lambda \xi)}{(n-1)}] = 0,$$
where $\kappa_{2} = [\varepsilon - \frac{r}{n(n-1)}]$

$$\kappa_{3} = [\varepsilon - \frac{(\phi \xi - \lambda \xi)}{(n-1)}] = 0,$$
where $\kappa_{3} = [\varepsilon - \frac{r}{n(n-1)}]$

$$\kappa_{3} = [\varepsilon - \frac{(\phi \xi - \lambda \xi)}{(n-1)}] = 0,$$
where $\kappa_{3} = [\varepsilon - \frac{r}{n(n-1)}]$

$$\kappa_{3} = [\varepsilon - \frac{(\phi \xi - \lambda \xi)}{(n-1)}] = 0,$$
where $\kappa_{3} = [\varepsilon - \frac{r}{n(n-1)}]$

$$\kappa_{3} = [\varepsilon - \frac{r}{n(n-1)}] = 0,$$

$$\kappa_{3} = [\varepsilon - \frac{r}{n(n-1)}$$

which shows that λ is shrinking. Thus we can state as follows -

Theorem (4.1): Ricci Soliton in (ε) -para Sasakian manifolds with ξ as space vector field satisfying $R(\xi, X).\overline{C} =$ 0, is shrinking.

5. Ricci Soliton in (ε) -Para Sasakian Manifold Satisfying $\bar{C}(\xi, X)$.S=0.

Let us suppose $\bar{C}(\xi, X)$.S=0, gives

$$S(\overline{C}(\xi, X)Y, Z) + S(Y, \overline{C}(\xi, X)Z) = 0.$$
(5.1)

By virtue of equation (2.21) above equation takes the form

In view of equations (2.17) and (2.18), above equation takes the form
$$-[\varepsilon + \frac{r}{n(n-1)}][g(X, Y)S(\xi, Z) + g(X, Z)S(Y, \xi)] + 2[\varepsilon + \frac{r\varepsilon}{n(n-1)}]\eta(Z)S(X, Y) = 0. \quad (5.2)$$
In view of equations (2.17) and (2.18), above equation takes the form

$$\left[\varepsilon + \frac{r^{1}}{n(n-1)}\right] \left[\lambda \varepsilon g(X, Y) \eta(Z) - \lambda \varepsilon g(X, Z) \eta(Y)\right] + 2\left[\varepsilon + \frac{r\varepsilon}{n(n-1)}\right] \eta(Z) S(X, Y) = 0.$$
 (5.3)

Putting $X=Y=e_i$, and taking summation over i, $1 \le i \le n$, we get

$$\left[\varepsilon + \frac{(\phi X - \lambda X)\varepsilon}{(n-1)}\right] n(\phi X - \lambda X) \eta(Z) = 0, \tag{5.4}$$

Taking Inner product with ξ , using equation (2.2), (2.3) and (2.4), we obtain

$$\lambda = 0$$
, or $\lambda < 0$,

which shows that λ is steady or shrinking .Thus we can state as follows -

Theorem (5.1): Ricci Soliton in (ε) -para Sasakian manifolds with ξ as space —like vector field satisfying $\bar{C}(\xi, X)$.S=0, is steady or shrinking.

6. Ricci Solitons in (ε) -Para Sasakian Satisfying $\bar{C}(\xi, X)$. R = 0.

Let $\overline{C}(\xi, X).R = 0$, then we have

$$\overline{\overline{C}}(\xi, X)R(Y, Z)U - R(\overline{\overline{C}}(\xi, X)Y, Z)U - R(Y, \overline{\overline{C}}(\xi, X)Z)U - \overline{\overline{C}}(Y, Z)R(\xi, X)U = 0.$$
(6.1)

By virtue of equation (2.21) above equation reduces to

$$\left[-\varepsilon + \frac{r}{n(n-1)}\right] \left[g(X, R(Y, Z)U)\xi - \varepsilon g(X, R(Y, Z)U)\xi - g(X, Y)R(\xi, Z)U - g(X, Z)R(Y, \xi)U\right]
+ \left[\varepsilon + \frac{r\varepsilon}{n(n-1)}\right] \left[\eta(R(Y, Z)U)X + \eta(Y)R(X, Z)U + \eta(Z)R(Y, Z)U\right]
+ \varepsilon g(X, U)\overline{C}(Y, Z)\xi - \varepsilon \eta(U)R(Y, Z)X = 0.$$
(6.2)

Taking the inner product of above equation with ξ and using equation (2.2) and (2.3), we get

$$\left[-\varepsilon + \frac{r}{n(n-1)}\right] [g(X, R(Y, Z)U) - \varepsilon g(X, R(Y, Z)U) - g(X, Y)\eta(R(\xi, Z)U)$$

$$-g(X, Z)\eta(R(Y, \xi)U)] + \left[\varepsilon + \frac{r\varepsilon}{n(n-1)}\right] \left[\eta(R(Y, Z)U)\eta(X) + \eta(Y)\eta(R(X, Z)U) + \eta(Z)\eta(R(Y, Z)U) \right] + \varepsilon g(X, U)\eta(\bar{C}(Y, Z)\xi) - \varepsilon \eta(U)\eta(R(Y, Z)X) = 0.$$
(6.3)

International Journal of Latest Engineering and Management Research (IJLEMR)

ISSN: 2455-4847

www.ijlemr.com || Volume 05 - Issue 07 || July 2020 || PP. 20-25

Using equations (2.16) and (2.23), $X=\xi$ in above equation, we obtain

$$\begin{bmatrix} -\epsilon + \frac{r}{n(n-1)} \end{bmatrix} [-g(X, \ U)\eta(Y) - g(Y, \ U)\eta(Z)) \\ -K_2 \{g(Z, \ U)\eta(Y) - 2\epsilon\eta(U)\eta(Y)\eta(Z) + g(Y, \ U)\eta(Z)\} \\ -\epsilon g(X, R(Y, Z)U) - g(X, Y)\eta(R(\xi, Z)U) - g(X, Z)\eta(R(Y, \xi)U)] \\ + \left[\epsilon + \frac{r\epsilon}{n(n-1)} \right] K_2 [(1+\epsilon)g(Z, \ U)\eta(Y) - 2\epsilon g(Y, U)\eta(Z)] = 0.$$
 (6.4) In view of equation $Y = Z = \xi$, above equation reduces to
$$\left[\epsilon + \frac{r\epsilon}{n(n-1)} \right] K_2 \eta(U) = 0.$$
 In virtue of equation (2.19), in putting $U = \xi$, we get
$$\left[\epsilon + \frac{r\epsilon}{n(n-1)} \right] \left[\epsilon - \frac{r}{n(n-1)} \right] = 0, \text{ where } r = n(\varphi X - \lambda X)$$
 $\lambda > 0$

$$\left[\varepsilon + \frac{\mathrm{r}\varepsilon}{n(n-1)}\right] \mathrm{K}_2 \eta(\mathrm{U}) = 0. \tag{6.5}$$

$$\left[\varepsilon + \frac{r\varepsilon}{n(n-1)}\right] \left[\varepsilon - \frac{r}{n(n-1)}\right] = 0, \text{ where } r = n(\phi X - \lambda X)$$

$$\lambda > 0,$$

which shows that λ is either steady or expanding. Thus we can state as follows -

Theorem (6.1): Ricci Soliton in (ε) -para Sasakian manifolds with ξ as space—like vector field satisfying $\bar{C}(\xi, X)$.R=0, is steady or expanding.

7. Ricci Soliton in (ε) -Para Sasakian Satisfying R (ξ, X) . $\overline{C} = 0$.

Let $R(\xi, X).\overline{C} = 0$, then we have

$$R(\xi, X)\overline{C}(Y, Z)U - \overline{C}(R(\xi, X)Y, Z)U - \overline{C}(Y, R(\xi, X)Z)U - \overline{C}(Y, Z)R(\xi, X)U = 0.$$

$$(7.1)$$

By virtue of equation (2.14) above equation reduces to

$$[-\varepsilon g(X, \overline{C}(Y, Z)U)\xi + \varepsilon \eta(\overline{C}(Y, Z)U)X] + \varepsilon g(X, Y)\overline{C}(\xi, Z)U -\varepsilon \eta(Y)\overline{C}(X, Z)U + \varepsilon g(X, Z)\overline{C}(Y, \xi)U) -\varepsilon \eta(Z)\overline{C}(Y, X)U +\varepsilon g(X, U)\overline{C}(Y, Z)\xi - \varepsilon \eta(U)\overline{C}(Y, Z)X] = 0.$$
 (7.2)

Taking the inner product of above equation with ξ , and using equation (2.2) and (2.3), we get

$$\begin{split} \left[\varepsilon g(\mathbf{X},\ \bar{\mathbf{C}}(\mathbf{Y},\ \mathbf{Z})\mathbf{U}) - \varepsilon \eta(\mathbf{X})\eta(\bar{\mathbf{C}}(\mathbf{Y},\ \mathbf{Z})\mathbf{U}) + g(\mathbf{X},\ \mathbf{Y})\eta(\bar{\mathbf{C}}(\xi,\ \mathbf{Z})\mathbf{U}) - \eta(\mathbf{Y})\eta(\bar{\mathbf{C}}(\mathbf{X},\ \mathbf{Z})\mathbf{U}) \\ + g(\mathbf{X},\ \mathbf{Z})\,\eta(\bar{\mathbf{C}}(\mathbf{Y},\ \xi)\mathbf{U}) - \eta(\mathbf{Z})\eta(\bar{\mathbf{C}}(\mathbf{Y},\ \mathbf{X})\mathbf{U}) \\ + g(\mathbf{X},\ \mathbf{U})\eta(\bar{\mathbf{C}}(\mathbf{Y},\ \mathbf{Z})\xi) - \eta(\mathbf{U})\eta(\bar{\mathbf{C}}(\mathbf{Y},\ \mathbf{Z})\mathbf{X})\right] = 0. \end{split} \tag{7.3}$$

Using equation (2.24) in above equation, we obtain
$$\varepsilon g(X, \overline{C}(Y, Z)U) = \left[\frac{r}{n(n-1)} + \varepsilon\right] \left[(1-\varepsilon) \left\{ g(X, Y)\eta(Z) + g(X, Z)\eta(Y) \right\} \eta(U) -2g(Y, U)\eta(X)\eta(Z) + g(X, Y)g(Z, U) - g(X, Z)g(Y, U) \right]. \tag{7.4}$$

$$-2g(Y, U)\eta(X)\eta(Z) + g(X, Y)g(Z, U) - g(X, Z)g(Y, U)]. \tag{7.4}$$
In view of equation (2.21), in $X = \xi$ above equation reduces to
$$\eta(\overline{C}(Y, Z)U) = \left[\frac{r}{n(n-1)} + \varepsilon\right][(1-\varepsilon)\{\eta(U)\eta(Y)\eta(Z) + (\varepsilon - 1)\varepsilon\eta(Z)\eta(Y)\}\eta(U)$$

$$-2g(Y, U)\eta(Z) + \varepsilon g(Z, U)\eta(Y) - g(Y, U)\eta(Z)]. \tag{7.5}$$

Now, putting
$$Y = U = \xi$$
, in above equation and by use equations (2.2), (2.3), (2.4) and (2.14), we obtain
$$\left[\frac{r}{n(n-1)} + \varepsilon\right](1+3\varepsilon)\eta(Z) = 0. \tag{7.6}$$

In view of equation (2.19), $Z=\xi$, we get

$$\left[\frac{\lambda}{(n-1)} + \varepsilon\right](1+3\varepsilon) = 0,$$
$$\lambda = -\varepsilon(n-1)$$

(7.7)

Now, suppose ξ is space –like vector field in (ε) -para Sasakian manifolds, then from equation (7.7), we obtain $\lambda < 0$,

which shows that λ is shrinking. Thus we can state as follows -

Theorem (7.1): Ricci Soliton in (ε) -para Sasakian manifolds with ξ as space-like vector field satisfying $R(\xi, X).\overline{C} = 0$, is shrinking.

Again if we assume vector field ξ as time-like vector field in (ε) -para Sasakian manifolds then, in view of equation (7.7), we obtain

$$\lambda > 0$$

which shows that λ is expanding. Thus we can state as follows -

Theorem (7.2) Ricci Solitons in (ε) -para Sasakian manifolds admitting ξ as time-like vector field satisfying $R(\xi, X).\overline{C} = 0$, is expanding.

References:

- [1]. C. S. Bagewadi, G. Ingalahalli and S. R. Ashoka (2013): A study on Ricci solitons in Kenmotsu manifolds, ISRN Geometry, Vol. 2013, Article ID 422593, 6 Pages.
- [2]. C. L. Bejan and M. Crasmareanu (2011): Ricci solitons in manifolds with quasi-contact curvature, Publ. Math. Debrecen, 78(1), 235-243.
- [3]. A. Bejancu and K. L. Duggal (1993): Real Hypersurface of indefinite Kahler manifolds, Int. Math. Sci., 16(3), 545-556.
- [4]. A. M. Blaga (2015): η-Ricci solitons on para-Kenmotsu manifolds, Balkan J. Geom. Appl., 20, 1-13.
- [5]. S. Chandra, S. K. Hui and A. A. Shaikh (2015): Second order parallel tensors and Ricci solitons on (LCS)_n-manifolds, Commun. Korean Math. Soc., 30, 123-130.
- [6]. B. Y. Chen and S. Deshmukh (2014): Geometry of compact shrinking Ricci solitons, Balkan J. Geom. Appl.,19,13-31.
- [7]. U. C. De and A. Sarkar (2009): On (ε) -Kenmotsu manifolds, Hadronic J., 32(2), 231-242.
- [8]. U.C. De and A. A. Shaikh (2009): Complex manifold and contact manifolds, Norosa Publishing House, Now Delhi.
- [9]. U. C. De, R. N. Singh and S. K. Pandey (2010): On the conharmonic curvature tensor of generalized Sasakian space forms, ISRN Geometry, 8, 1-10.
- [10]. S. Deshmukh, H. Al-Sodais and H. Alodan (2011): A note on Ricci solitons, Balkan J. Geom. Appl.,16, 48-55.
- [11]. R. Hamilton (1982): Three manifolds with positive Ricci curvature, J. Differential Geom. 17 (2), 254-306.
- [12]. R. Hamilton (1982): Four manifolds with positive curvature operator, J. Differential Geom. 24 (2), 153-179.
- [13]. C. He and M. Zhu (2011): Ricci solitons on Sasakian manifolds, arxiv: 1109.4407V2, [Math DG].
- [14]. S. K. Hui and D. Chakraborty (2018): Ricci almost Solitons on concircular Ricci pseudosymmetric β –Kenmotsu manifolds, Hacettepe Journal of Mathematics and Statistics volume 47,579-587.
- [15]. H. G. Nagaraja and C. R. Premalatha (2012): Ricci solitons in Kenmotsu manifolds, Journal of Mathematical Analysis, 3, 18-24.
- [16]. S. K. Pandey, G. Pandey, K. Tiwari and R. N. Singh (2014): On a semi-symmetric non-metric connection in an indefinite para Sasakian manifolds ,Journal of Mathematics and Computer Sciences 12,159-172.
- [17]. S. K. Pandey, R. L. Patel and R. N. Singh (2017): Ricci Solitons in an (ε)-Kenmotsu Manifold Admitting Conharmonic Curvature Tensor International Journal on Recent and Innovation Trends in Computing and Communication, 5,(11),75-85.
- [18]. R. L. Patel S. K. Pandey and R. N. Singh (2018): Ricci Solitons on (ε) -Para Sasakian manifolds International journal of Mathematics And its Applications 6,(1-A),73-82.
- [19]. R. L. Patel S. K. Pandey and R. N. Singh (2018): On Ricci Solitons in (ε)-Kenmotsu manifolds International Journal of Engineering Sciences and Management Research, 5, (2),17-23.
- [20]. R. Sharma (2008): Certain results on K-contact and (k, μ)-contact manifolds, Journal of Geometry, 89 (1-2), 138-147.
- [21]. R. N. Singh, S. K. Pandey, G. Pandey and K. Tiwari (2014): On a semi-symmetric metric connection in an (ε)-Kenmotsu manifold, Commun. Korean Math. Soc., 29(2),331-343.
- [22]. X. Xufng and C. Xiaoli (1998): Two theorems on (ε) -Sasakian manifolds, Internat. J. Math. Sci., 21(2), 245-254.